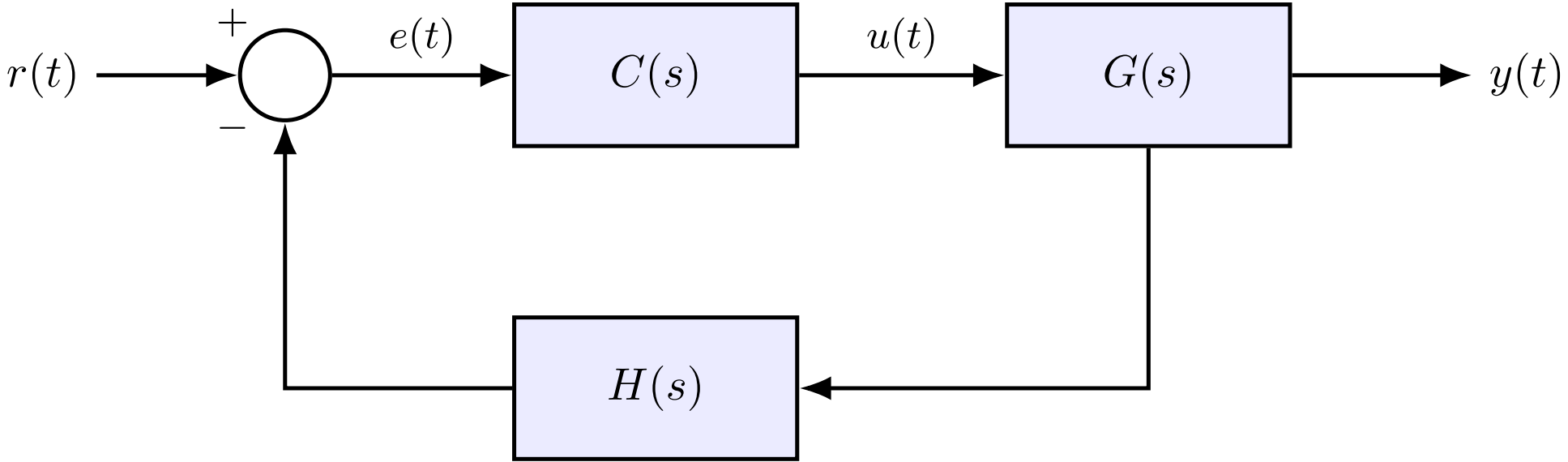
$r(t)$
+
−
$e(t)$
$C(s)$
$u(t)$
$G(s)$
$y(t)$
$H(s)$