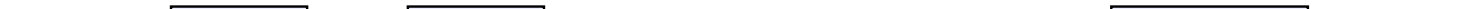
X(s)
G1(s)
G2(s)
Y(s)
≡
X(s)
G1(s) G2(s)
Y(s)