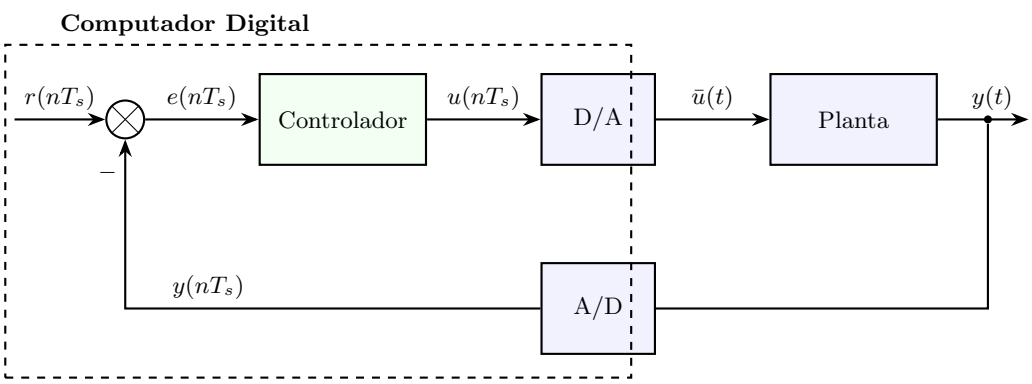
Computador Digital
$r(nT_s)$
$e(nT_s)$
Controlador
$u(nT_s)$
D/A
$\bar{u}(t)$
Planta
$y(t)$
−
$y(nT_s)$
A/D