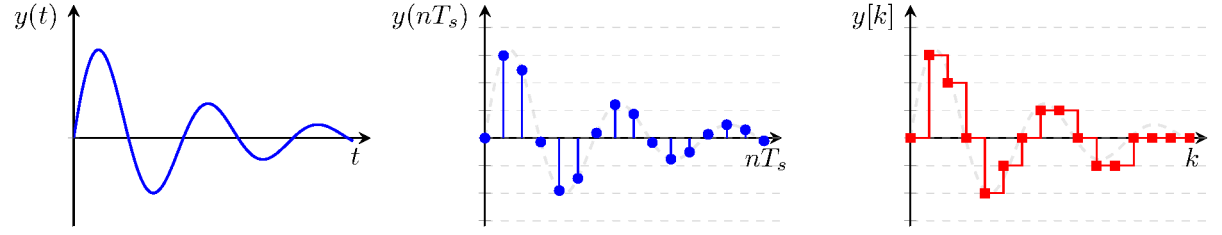Contínuo: $y(t)$ **Amostrado:** $y(nT_s)$ **Digital:** $y[k]$