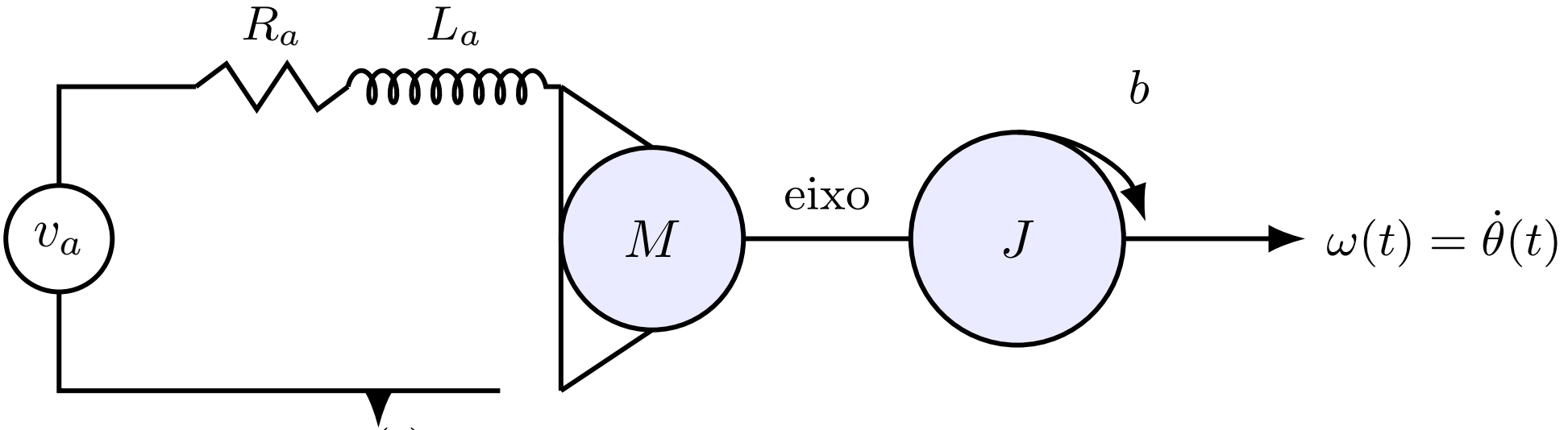
R_a
L_a
b
v_a
M
eixo
J
$\omega(t) = \dot{\theta}(t)$
$i_a(t)$ f.c.e.m. $e_b = K_b\,\omega$