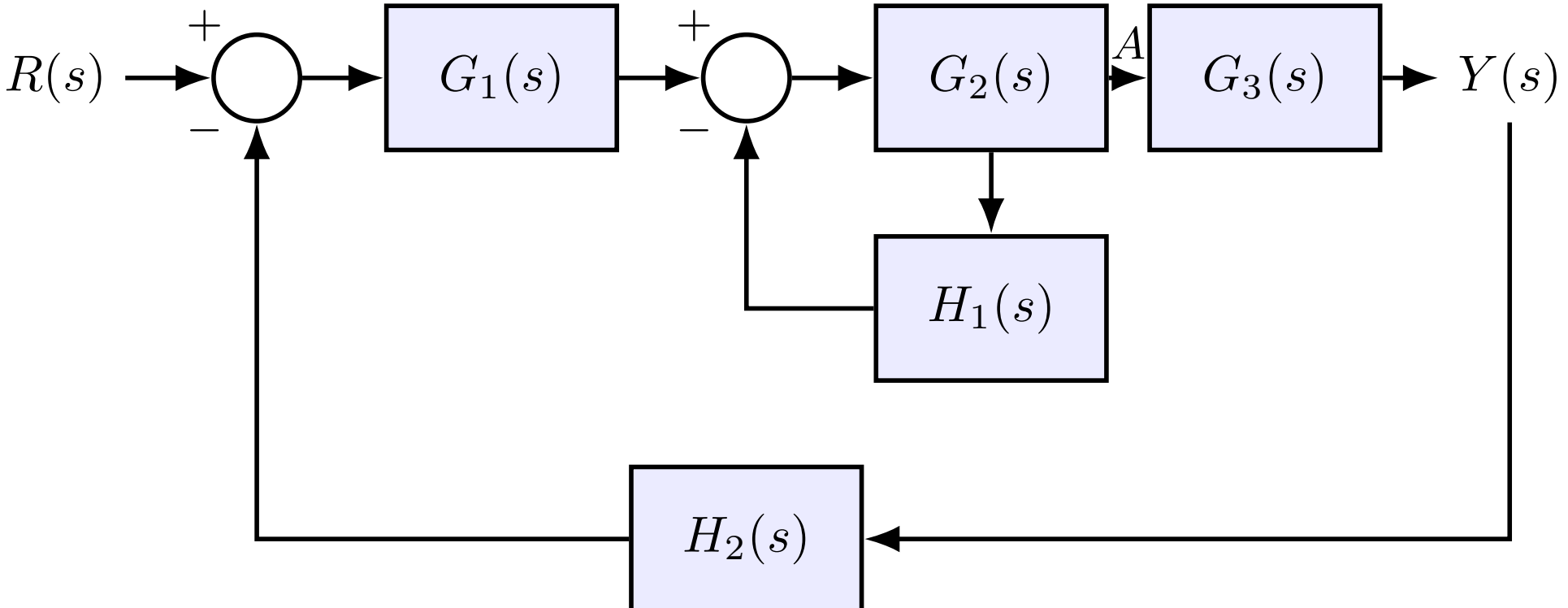
$R(s)$
+
−
$G_1(s)$
+
−
$G_2(s)$
A
$G_3(s)$
$Y(s)$
$H_1(s)$
$H_2(s)$