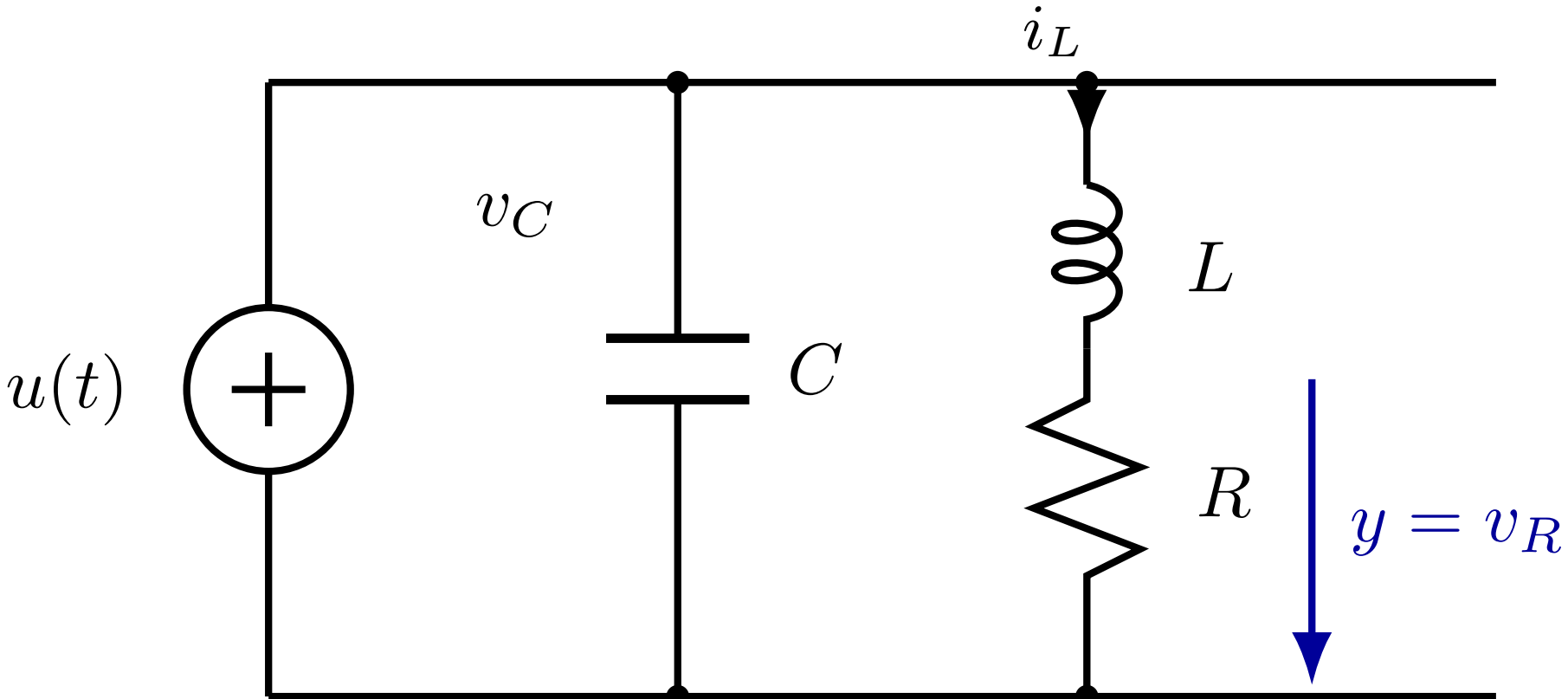
i_L
v_C
L
$u(t)$
C
R
$y = v_R$